

# An Extended Integrated Assessment Model for Mitigation and Adaptation Policies on Climate Change

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# Overview: Mitigation and Adaption

- Builds on previous Models with Alfred Greiner, Lars Gruene and Helmut Maurer
- Builds on Bonen, Loungani and Semmler, IMF paper (2016)
- Extended IAM: 5 State Variables; up to 6 Control Variables; Finite Time; Parameter Uncertainty
- Explores numerically
  - Proper balance of spending for mitigation, adaptation and productive infrastructure
  - Decreasing efficiency of fossil fuel energy use
  - Decreasing returns from mitigation efforts
  - Variation in discount rate
- Simplified Model: Financing of Climate Change Policies with intertemporal Burden Sharing (Jeff Sachs 2014, Gevorkyan et al., 2016)

# Model of Mitigation and Adaptation to Climate Change

State variables, IAM only  $K$ ,  $T$ ,  $M$  :

- $K$  : private capital per capita,
- $g$  : public capital per capita,
- $b$  : country's level of debt,
- $R$  : non-renewable resource ,
- $M$  : GHG (Green House Gas) concentration in the atmosphere.

Control variables:

- $C$  : per capita consumption,
- $e_p$  : government's net tax revenue,
- $u$  : extraction rate from the non-renewable resource,

The stock of public capital  $g$  is allocated among three uses:

- $\nu_1$  : standard infrastructure,
- $\nu_2$  : climate change adaptation,
- $\nu_3$  : climate change mitigation (IAM;  $\mu$ ),

$$\nu_1, \nu_2, \nu_3 \geq 0, \quad \nu_1 + \nu_2 + \nu_3 = 1.$$

# Dynamic Model of Adaptation and Mitigation

Production function  $Y = A(A_K K + A_U u)^\alpha \cdot (\nu_1 g)^\beta$

Dynamical system

$$\begin{aligned}\dot{K} &= Y - C - e_p - (\delta_K + n)K - u\psi R^{-\tau}, & K(0) &= K_0, \\ \dot{g} &= \alpha_1 e_p + i_F - (\delta_g + n)g, & g(0) &= g_0, \\ \dot{b} &= (\bar{r} - n)b - (1 - \alpha_1 - \alpha_2 - \alpha_3) \cdot e_p, & b(0) &= b_0 \\ \dot{R} &= -u, & R(0) &= R_0 \\ \dot{M} &= \gamma u - \mu(M - \kappa \tilde{M}) - \theta(\nu_3 \cdot g)^\phi, & M(0) &= M_0.\end{aligned}$$

State variable :  $X = (K, g, b, R, M) \in \mathbf{R}^5$

Control variable :  $U = (C, e_p, u) \in \mathbf{R}^3$

Control System :  $\dot{X} = f(X, U), \quad X(0) = X_0$

Planning Horizon :  $[0, T]$ , terminal time  $T > 0$

# Welfare Functional and Optimal Control Problem

## Optimal Control Problem

Maximize the **welfare functional**

$$W(T, X, U) = \int_0^T e^{-(\rho-n)\cdot t} \cdot \frac{(C(\alpha_2 e p)^\eta (M - \tilde{M})^{-\epsilon} (\nu_2 g)^\omega)^{1-\sigma} - 1}{1-\sigma} dt$$

such that for all  $t \in [0, T]$  :

$$\dot{X}(t) = f(X(t), U(t)), \quad X(0) = X_0,$$

$$0 \leq u(t) \leq u_{max},$$

$$K(t) \geq 0, \quad R(t) \geq 0.$$

Further constraints:

**terminal constraint** :  $K(T) = K_T \geq 0$

**state constraint** :  $M(t) \leq M_{max} \quad \forall t \in [0, T].$

# Model Parameters

Parameter	Value	Definition
$\rho$	0.03	Pure discount rate
$n$	0.015	Population Growth Rate
$\eta$	0.1	Elasticity of transfers and public spending in utility
$\epsilon$	1.1	Elasticity of $CO_2$ -eq concentration in (dis)utility
$\omega$	0.05	Elasticity of public capital used for adaptation in utility
$\sigma$	1.1	Intertemporal elasticity of instantaneous utility
$A$	$\in [1, 10]$	Total factor productivity
$A_K$	1	Efficiency index of private capital
$A_u$	$\in [50, 500]$	Efficiency index of the non-renewable resource
$\alpha$	0.5	Output elasticity of privately-owned inputs, $A_k k + A_u u$
$\beta$	0.5	Output elasticity of public infrastructure, $\nu_1 g$
$\psi$	1	Scaling factor in marginal cost of resource extraction
$\tau$	2	Exponential factor in marginal cost of resource extraction
$\delta_K$	0.075	Depreciation rate of private capital
$\delta_g$	0.05	Depreciation rate of public capital
$i_F$	0.05	Official development assistance earmarked for public infrastructure
$\alpha_1$	0.1	Proportion of tax revenue allocated to new public capital
$\alpha_2$	0.7	Proportion of tax revenue allocated to transfers and public consumption
$\alpha_3$	0.1	Proportion of tax revenue allocated to administrative costs
$\bar{r}$	0.07	World interest rate (paid on public debt)
$\tilde{M}$	1	Pre-industrial atmospheric concentration of greenhouse gases
$\gamma$	0.9	Fraction of greenhouse gas emissions not absorbed by the ocean
$\mu$	0.01	Decay rate of greenhouse gases in atmosphere
$\kappa$	2	Atmospheric concentration stabilization ratio (relative to $\tilde{M}$ )
$\theta$	0.01	Effectiveness of mitigation measures
$\phi$	$\in [0.2, 1]$	exponent in mitigation term ( $\nu_3 g$ ) $^\phi$

- Dynamic Model for Mitigation and Adaptation to Climate Change: Parameter Uncertainty, Homotopic Solutions
- 1. Initial Conditions and Constraints, Controls
- 2. Comparison: Fixed and optimal values of  $\nu_1, \nu_2, \nu_3$
- 3. Numerics: Efficiency Index  $A_u, A_u = 100, 200, 500, \phi = 1$
- 4. Numerics: Mitigation Efficiency,  $\phi = 1$ , or  $0.2 \leq \phi \leq 1$
- 5. Numerics: Discount Rate,  $0.02 \leq \rho \leq 0.1$

# 1. Initial conditions, constraints, choice of $\nu_1, \nu_2, \nu_3$

## Initial conditions

$$K(0) = 1.5, g(0) = 0.5, b(0) = 0.8, R(0) = 1.5, M(0) = 1.5.$$

**Control constraint** :  $0 \leq u(t) \leq 0.1 \quad \forall t \in [0, T].$

**Terminal constraint** :  $K(T) = K_T = 3.$

**Strategy 1** : Choose **fixed values**  $\nu_1 = 0.6, \nu_2 = 0.2, \nu_3 = 0.2.$

**Strategy 2** : Consider  $\nu_1, \nu_2, \nu_3$  as additional **optimization variables** satisfying the constraints  $\nu_1 + \nu_2 + \nu_3 = 1.$

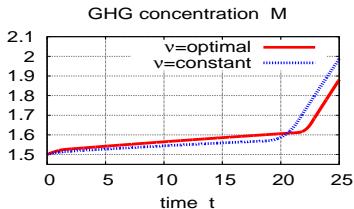
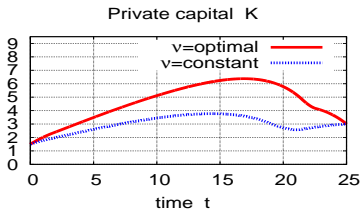
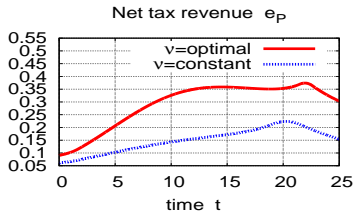
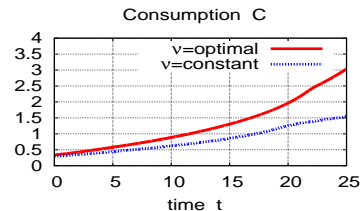
**Strategy 3** : Consider  $\nu_1 = \nu_1(t), \nu_2 = \nu_2(t), \nu_3 = \nu_3(t), t \in [0, T],$  as **control functions** satisfying the constraints  $\nu_1(t) + \nu_2(t) + \nu_3(t) = 1 \quad \forall t.$

Strategy 3 improves only slightly on Strategy 2 and will be discarded in the numerical results.



## 2. Comparison : fixed and optimal values of $\nu_1, \nu_2, \nu_3$

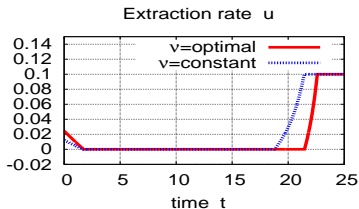
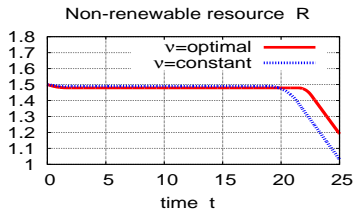
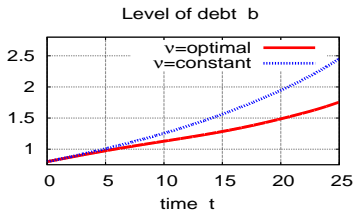
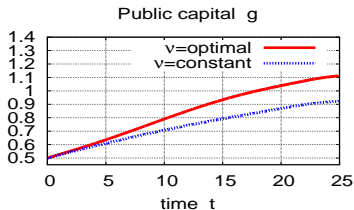
Exponent  $\phi = 1$  and efficiency index  $A_U = 50$  :



optimal values  $\nu_1 = 0.9534$ ,  $\nu_2 = 0.04662$ ,  $\nu_3 = 0$  :  $W(T) = 5.1086$   
 fixed values  $\nu_1 = 0.6$ ,  $\nu_2 = 0.2$ ,  $\nu_3 = 0.2$  :  $W(T) = -2.1006$

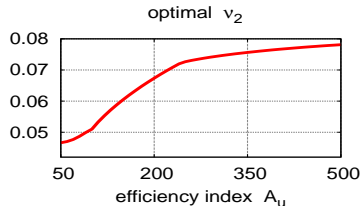
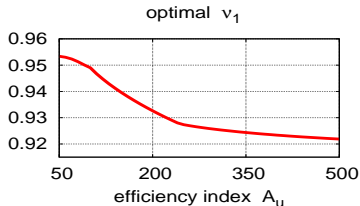
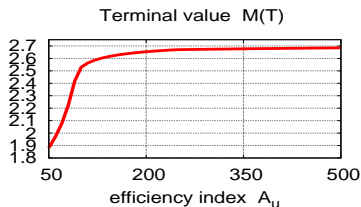
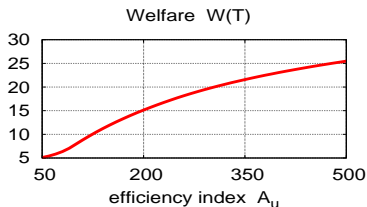
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Exponent  $\phi = 1$  and efficiency index  $A_U = 50$  :



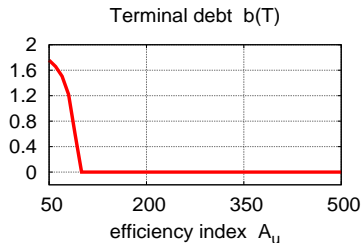
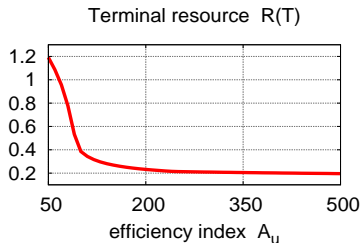
optimal values  $\nu_1 = 0.9534$ ,  $\nu_2 = 0.04662$ ,  $\nu_3 = 0$  :  $W(T) = 5.1086$   
 fixed values  $\nu_1 = 0.6$ ,  $\nu_2 = 0.2$ ,  $\nu_3 = 0.2$  :  $W(T) = -2.1006$

### 3. Numerics: Efficiency Index, fossil energy, for homotopy $A_U \in [50, 500]$



Terminal values  $W(T)$  and  $M(T)$  and optimal parameters  $\nu_1, \nu_2$ .

### 3. Numerics: Efficiency Index, for homotopy $A_u \in [50, 500]$

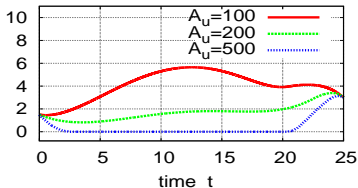


Terminal values  $R(T)$  and  $b(T)$  for  $A_u \in [50, 500]$

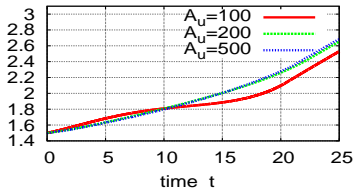
### 3. Numerics: Efficiency Index, Solutions for $A_U = 100, A_U = 200, A_U = 500$

,  $\phi = 1$

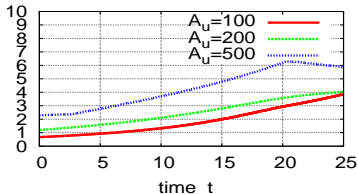
Private capital K



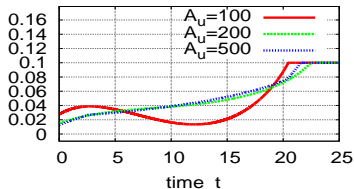
GHG concentration M



Consumption C

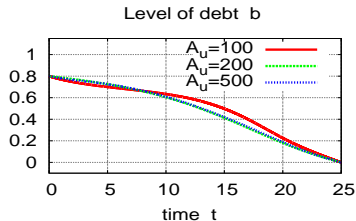
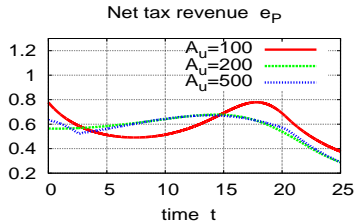
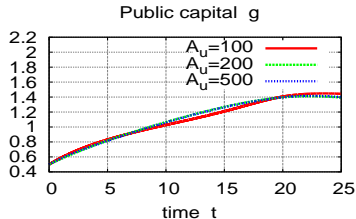
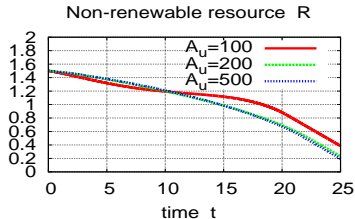


Extraction rate u



### 3. Numerics: Efficiency Index, Solutions for $A_U = 100, A_U = 200, A_U = 500$

,  $\phi = 1$



## 4. Numerics: Mitigation Exponent, $0.2 \leq \phi \leq 1$

Consider the **mitigation exponent**  $0.2 \leq \phi \leq 1$  in

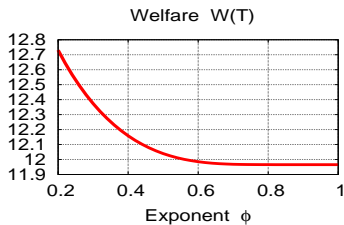
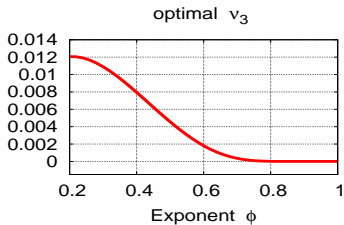
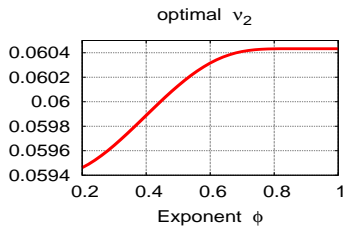
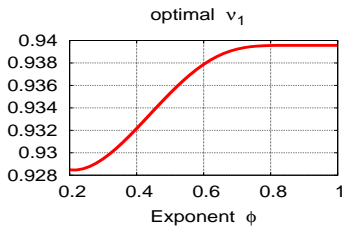
$$\dot{M} = \gamma u - \mu(M - \kappa \tilde{M}) - \theta(\nu_3 \cdot g)^\phi.$$

For  $\phi = 1$  we always obtain  $\nu_3 = 0$ . However, for

$$\phi \leq \phi_0 \approx 0.88$$

we obtain  $\nu_3 > 0$ . These findings can be confirmed by computing optimal solutions via a **homotopy** with respect to  $\phi \in [0.2, 1]$ .

# 4. Numerics: Mitigation Exponent, Homotopy for $\phi \in [0.2, 1]$ with $A_U = 150$

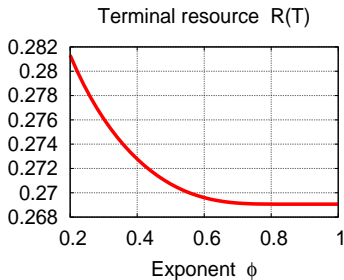
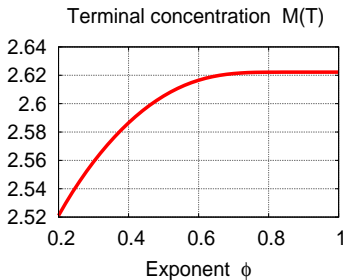


$\phi \in [0.2, 1]$  : optimal values  $\nu_1, \nu_2, \nu_3$  and welfare  $W(T)$  .





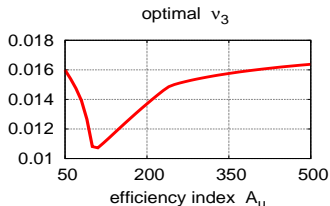
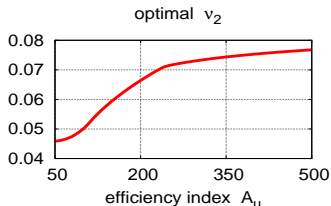
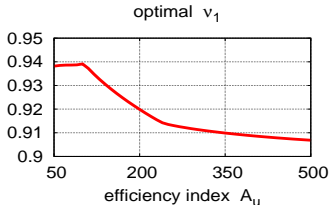
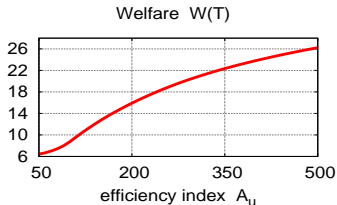
## 4. Numerics: Mitigation Exponent, Homotopy for $\phi \in [0.2, 1]$ with $A_U = 150$



$\phi \in [0.2, 1]$  : terminal values  $M(T)$  and  $R(T)$  .

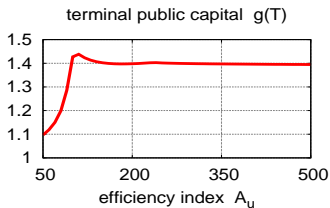
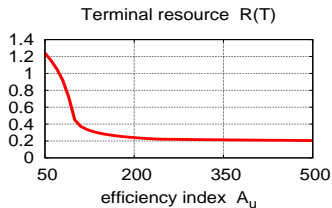
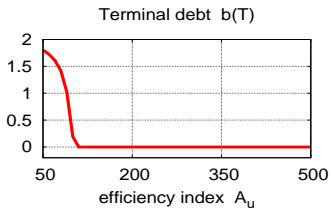
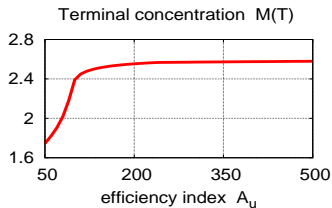
# 4. Numerics: Mitigation Exponent, $\phi = 0.2$ : terminal values for homotopy $A_u \in [50, 500]$

$\phi = 0.2$  : homotopy parameter  $50 \leq A_u \leq 500$



Welfare  $W(T)$  and optimal parameters  $v_1, v_2, v_3$

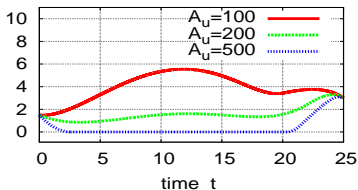
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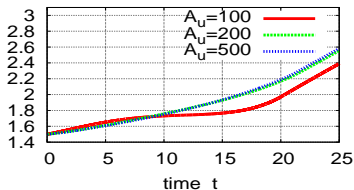
Terminal values  $M(T)$ ,  $R(T)$ ,  $b(T)$ ,  $g(T)$  depending on  $A_U$

# 4. Numerics: Mitigation Exponent, $\phi = 0.2$ : Solutions for $A_U = 100, A_U = 200, A_U = 500$

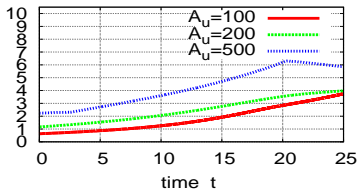
Capital K



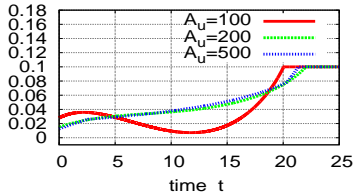
CO<sub>2</sub> concentration M



Consumption C

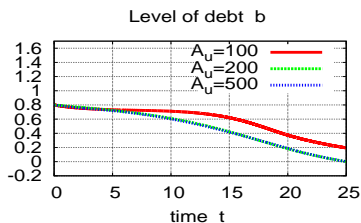
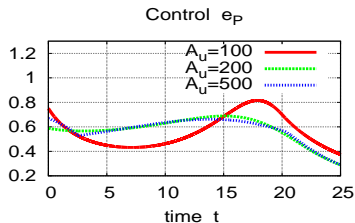
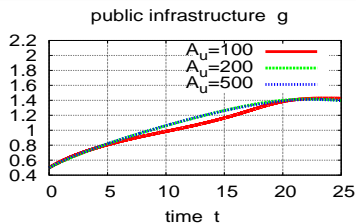
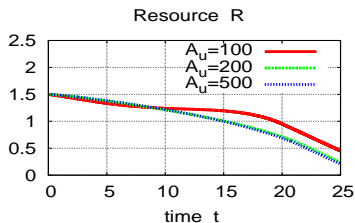


Extraction rate u



$\phi = 0.2$  : comparing solutions for  $A_U = 100$ ,  $A_U = 200$ ,  $A_U = 500$ .

# 4. Numerics: Mitigation Exponent, $\phi = 0.2$ : Solutions for $A_U = 100, A_U = 200, A_U = 500$

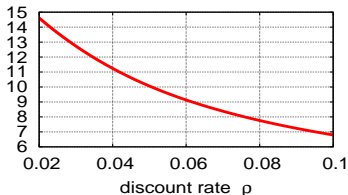


$\phi = 0.2$  : comparing solutions for  $A_U = 100$ ,  $A_U = 200$ ,  $A_U = 500$ .

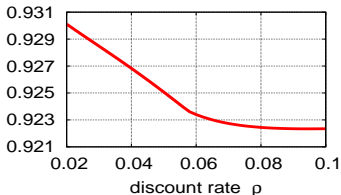
# 5. Numerics: Discount Rate, $\phi = 0.2$ : terminal values for homotopy $\rho \in [0.02, 0.1]$

$\phi = 0.2$  : homotopy for dicount rate  $0.02 \leq \rho \leq 0.1$

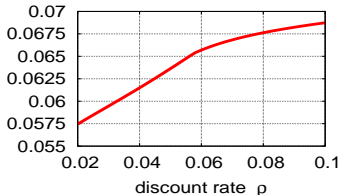
Welfare  $W(T)$



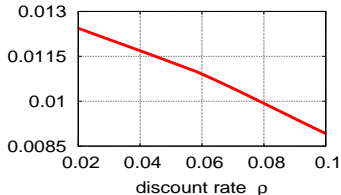
optimal  $v_1$



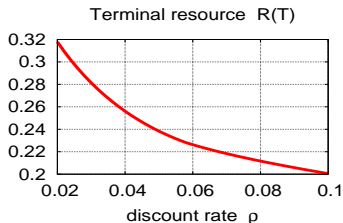
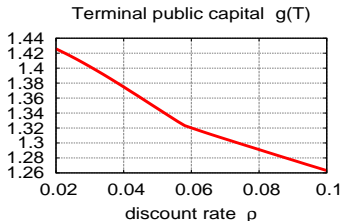
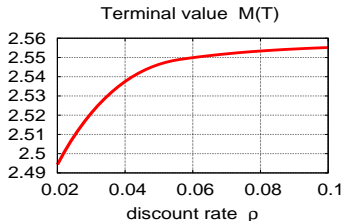
optimal  $v_2$



optimal  $v_3$



## 5. Numerics: Discount Rate, $\phi = 0.2$ : terminal values for homotopy $\rho \in [0.02, 0.1]$



Terminal values  $M(T)$ ,  $R(T)$ ,  $g(T)$

# Simplified Model—Financing of Climate Policies through Burden Sharing

Sachs (2014), Gevorkyan et al. (2016), Solved with NMPC, see Gruene et al (2015)

Phase 1: Business As Usual (BAU, no carbon tax or climate bonds)

$$\text{Max}_C \int_{t=0}^N e^{-\rho t} \ln(C) dt$$

$$\dot{K} = D \cdot Y - C - (\delta + n)K$$

$$\dot{M} = \beta E - \mu M$$

$$E = \left( \frac{aK}{A_0} \right)^\gamma$$

$$D(\cdot) = (a_1 \cdot M^2 + 1)^{-\psi}$$



# Simplified Model—Financing of Climate Policies through Burden Sharing

Phase 2: Carbon tax, and green bonds

$$\text{Max}_C \int_{t=0}^N e^{-\rho t} \ln(C) dt$$

$$\dot{K} = D \cdot Y - C - \chi \cdot Y - (\delta + n)K$$

$$\dot{M} = \beta E - \mu M$$

$$\dot{b} = r \cdot b + A$$

$$E = \left( \frac{aK}{5(A + \chi \cdot Y) + A_0} \right)^\gamma$$

$$\chi = b_1 \frac{2}{\pi} \text{atan}(b_2 M^2 - 0.01)$$

# Simplified Model—Financing of Climate Policies through Burden Sharing

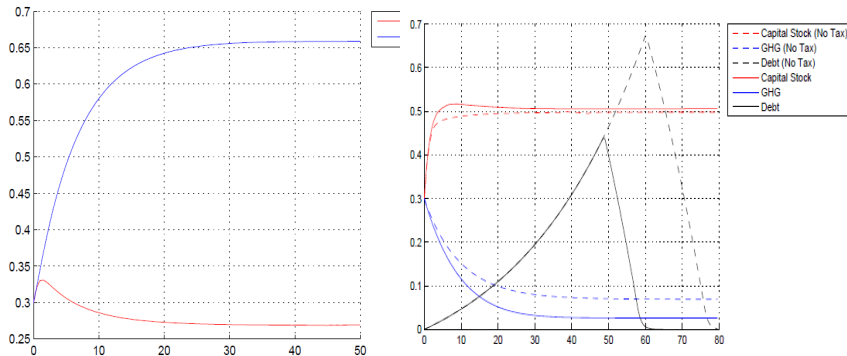
Phase 3: Debt repayment after elimination of carbon emission

$$\dot{K} = Y(1 - \tau) - C - \chi \cdot Y - (\delta + n)K$$

$$\dot{b} = r \cdot b - \tau Y$$

# Numerical Results for the 3 Phases

Left: BAU, right: Phase 2 (tax and no tax) and phase 3 (debt repayment)



Issue: Integrating all three phases into one model, Welfare computation with optimal switches

# Conclusion

- Developing a Macro Framework for Climate Policies (Extended IAM)
- Control Model with 5 State Variables, up 6 Controls Variables, Finite Time
- Exploration of Parameter Uncertainty using AMPL
- Simplified Model: Financing of Climate Policies through Intertemporal Burden Sharing
  - Implementation of cap and trade, carbon tax, and climate bonds
  - Phasing in of climate bonds under current macroeconomic/financial conditions
- Calibration for North-South Countries?

# Thank you for your attention